Alternate Pitch Mechanism Assembly Checklist



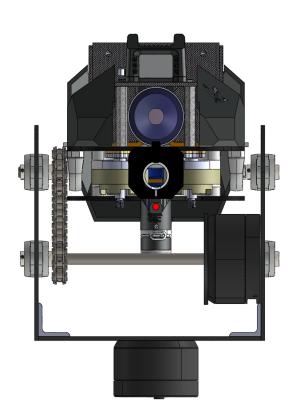
RoboMaster 2020-2021

Written by Roger Nguyen Contributors: Roger Nguyen

Old Configuration

Alternate Configuration





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Design Parameters

Summary			
Constraint	Status		
Power Consumption is under Maximum			
Power Supply Voltage is under Maximum			
Weight is under Maximum			
Size is under Maximum			

Key				
	Satisfied			
	Needs testing			
	Not satisfied			

RoboMaster Build Specifications: Basic Robot Information for Sentry

- Maximum Power Consumption is 30 W
- Maximum Power Supply Voltage is 30 V
- Maximum Weight not including Referee System is 15 kg
- Maximum Size (LWH and in mm) is either: 500/600/850 or 850/500/600

TR Target Specifications

- Drive the pitch motion of RM21 Infantry Turret with linkage or another form of connection
- Make the alternate configuration more space efficient → current pitch configuration is not very efficient spacing-wise

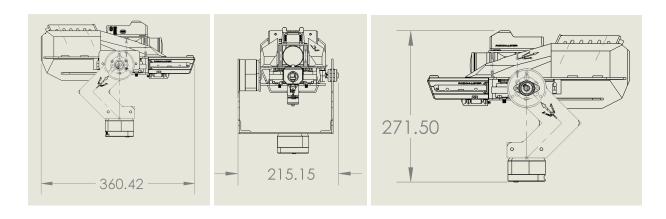
Hardware/Electronic Components

RoboMaster GM6020 Brushless DC Motor

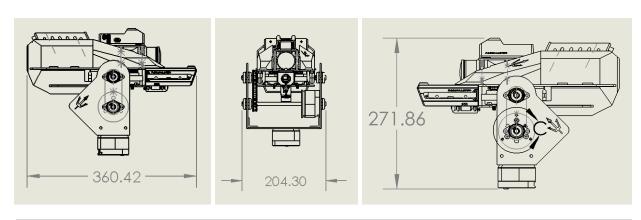
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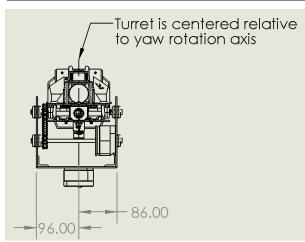
Current Dimensions (mm)

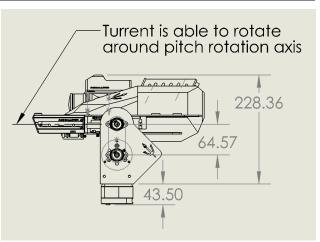
Old Configuration Size (LWH)



New Configuration Size (LWH)







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Current Design Specifications

• Design Specific Parameters:

- Yaw is Direct-Driven
- Pitch is not Direct-Driven

• Important Analysis Parameters:

- Weight of Top Plate (and Objects Supported by Top Plate)
- Moment of Inertia of Top Plate (and Objects Supported by Top Plate)
- o Moment of Inertia of Motor and Long Shaft
- Moment of Inertia of Top Plate (and Objects Supported by Top Plate) and Short Shaft
- o https://www.parktool.com/blog/repair-help/chain-length-sizing

• Torque Requirements:

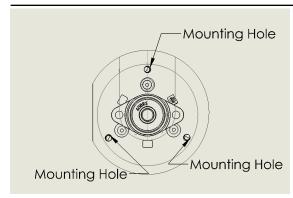
- The GM 6020 offers maximum continuous torque of 1.24 Nm and a stall torque of 1.6 Nm
- The torque generated by mass weight should not exceed the equivalent of 0.7-0.9 Kg at a distance 180 mm away from the pitch axis.
- o RoboMaster GM6020 Brushless DC Motor User Guide.pdf

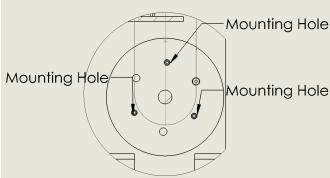
Mounting:

- Relies on GM 6020 Motor bottom mounting points (x3 M4)
 - REQUIRED PATTERN FOR RM 6020 Mounting (Contact Pres.)

Bottom of Motor Mounting on the Side Plate

Top of Motor Mounting on Connector





Wiring

- Total of 6 wires w/ total of
 - x2 CAN Cable: Pitch+Yaw Motor (2 lines)
 - x2 Power Cable (2 lines)
 - x2 PMW Cable (2 lines)

• Weight of Major Components

- Weight of Motor = 468 g
- Weight of Top Plate (and Objects Supported by Top Plate) = 1264.62 g
- Weight of Long Shaft (200 mm) = 78.87 g
- Weight of Short Shaft (50 mm) = 19.68 g
- Weight of Sprocket = 20.78 g
- Weight of 1ft Chain = 81.77 g

Extra Notes

None

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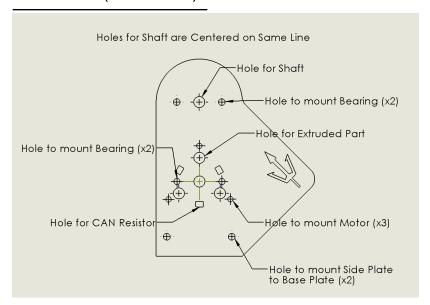
Critical Sections

Side Plates

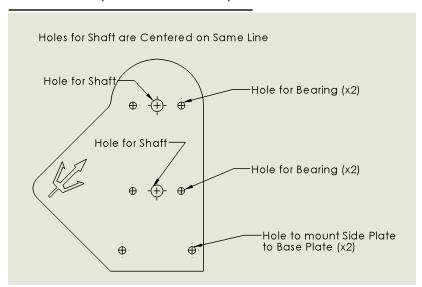
Notes:

- Holes for Shaft are Centered on the Same Line
- Holes for Bearing are Centered on the Same Line

Side Plate (Motor Side)

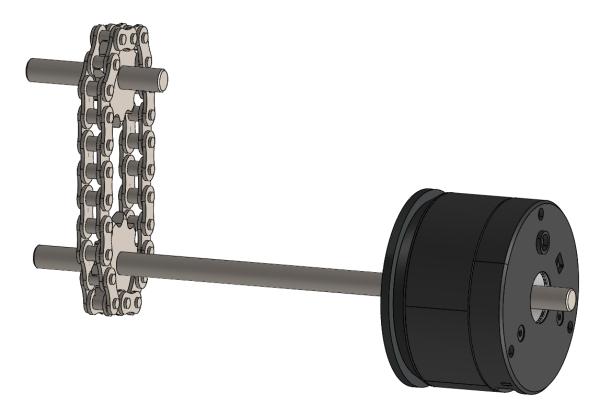


Side Plate (Non-Motor Side)



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Chain Link Mechanism



Components

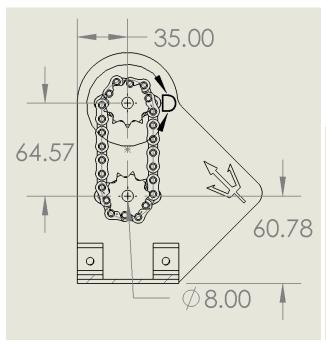
- RoboMaster GM6020 Brushless DC Motor
- Long Shaft
- Short Shaft
- x2 Sprocket
- Chain Link
- Motor Connector Plate

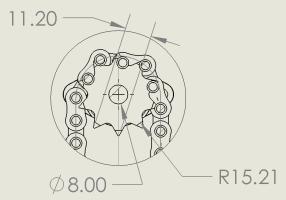
Features

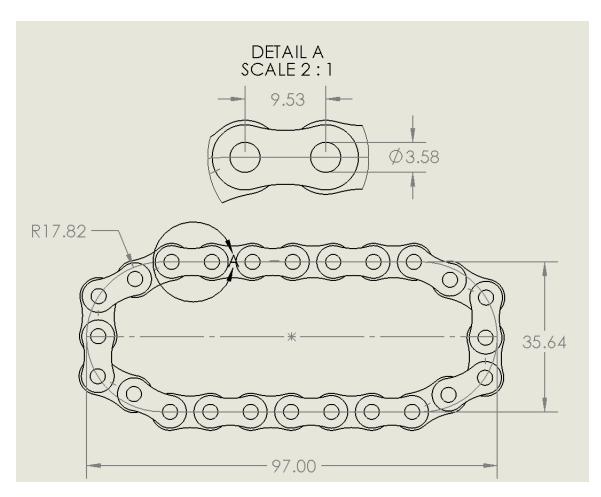
- Pitch Mechanism is Chain-Driven
- Chain Drive Advantages
 - Positive Drive
 - Lessens Load on Motor Compared to Direct Drive
- Chain Drive Disadvantages
 - o 98% Power and Torque Transfer Efficiency Compared to Direct Drive
 - Noisy and can cause Vibrations
 - Driving and Driven Shafts and Sprockets must be perfectly aligned

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Dimension (mm)







Analysis

• Alternate Pitch Configuration Calculations

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Work In Progress

Mounting Name	Description	Assignment	Status
None	None	None	Satisfied

Extra Stuff

Mounting Name	Quantity	Туре	Status
KFL08 Bearing	6	M5 Clearance Hole	Needs Optimization
KP08 Bearing (Pitch Mount)	2 (w/ linear pattern x4)	M4 Clearance Hole	Needs Optimization
RoboMaster GM6020 Brushless DC Motor	6	M3 Clearance Hole	Needs Optimization

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Manufacturing Process

None

B.O.M

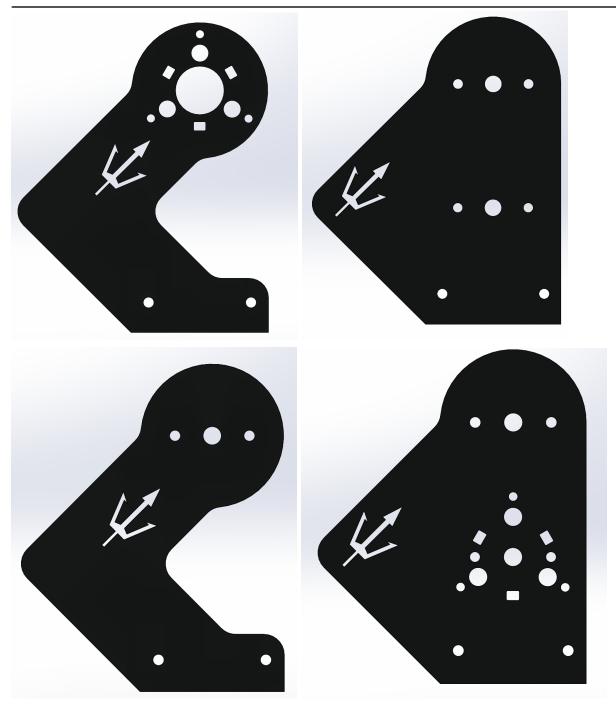
- Alternate Pitch Configuration BOM
- Cutting of Sheet Metal Cost not Included
- Expected Cost: \$69.61
 - o Includes Screw and Nut Costs from Home Depot

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Before & After Photos

Old Configuration

Alternate Configuration



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